

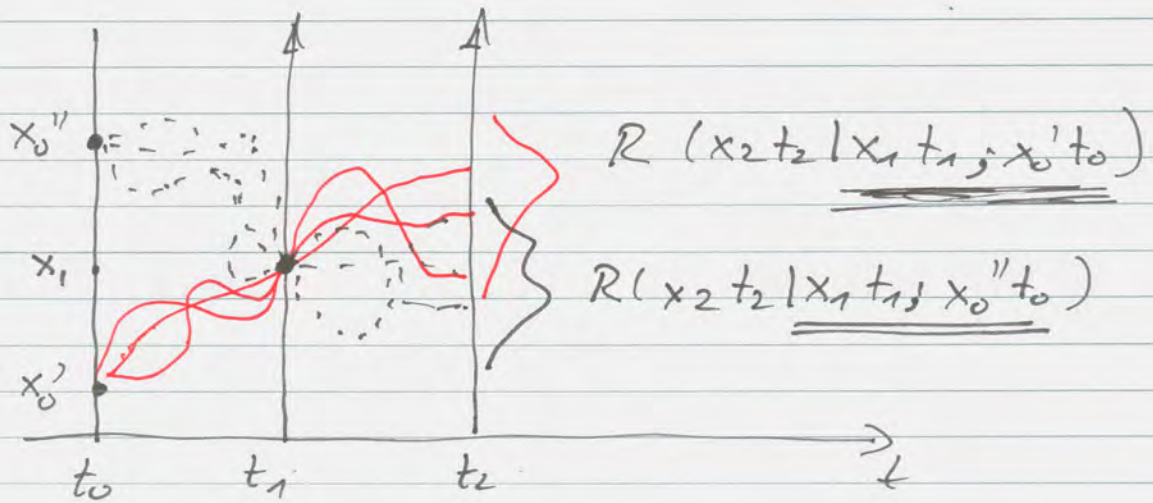
Lecture

I

① + ②

Fluctuation Theorems

- (1) Response Theory & Fluctuations
- (2) A Primer on the 2nd Law
- (3) Work-Theorems (mostly, classical)
& Relation to the Second Law



Note $R(x_2 t_2 | x_1 t_1)$ depends generally on $p_0(x_0)$

e.g. $p_0(x_0) = \delta(x - x_0')$

$$R(x_2 t_2 | x_1 t_1) = \frac{p_2(x_2 t_2, x_1 t_1)}{p(x_1 t_1)}$$

$$p(x_1 t_1) = \int R(x_1 t_1 | x_0 t_0) p_0(x_0) dx_0$$

$$p_2(x_2 t_2, x_1 t_1) = \int \frac{p_3(x_2 t_2, x_1 t_1, x_0 t_0)}{p_2(x_1 t_1, x_0 t_0)} \cdot \frac{p_2(x_1 t_1, x_0 t_0)}{p_0(x_0)} \cdot p_0(x_0) dx_0$$

$$= \int R(x_2 t_2 | x_1 t_1, x_0 t_0) \cdot R(x_1 t_1 | x_0 t_0) p_0(x_0) dx_0$$

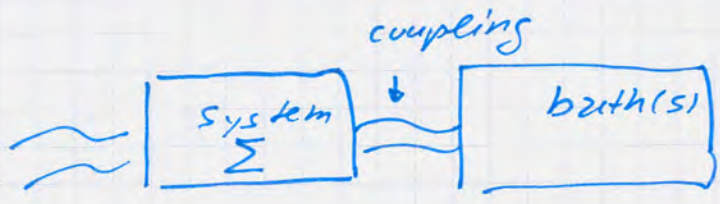
$$\neq \delta(x_0 - x_0')$$

$$= R(x_2 t_2 | x_1 t_1, x_0' t_0) p(x_1 t_1)$$

$$\Rightarrow \underline{R(x_2 t_2 | x_1 t_1)} = \frac{p_2(x_2 t_2, x_1 t_1)}{p(x_1 t_1)} = \underline{R(x_2 t_2 | x_1 t_1, x_0' t_0)}$$

$R(x_2 t_2 | x_1 t_1)$ depends on p_0 !

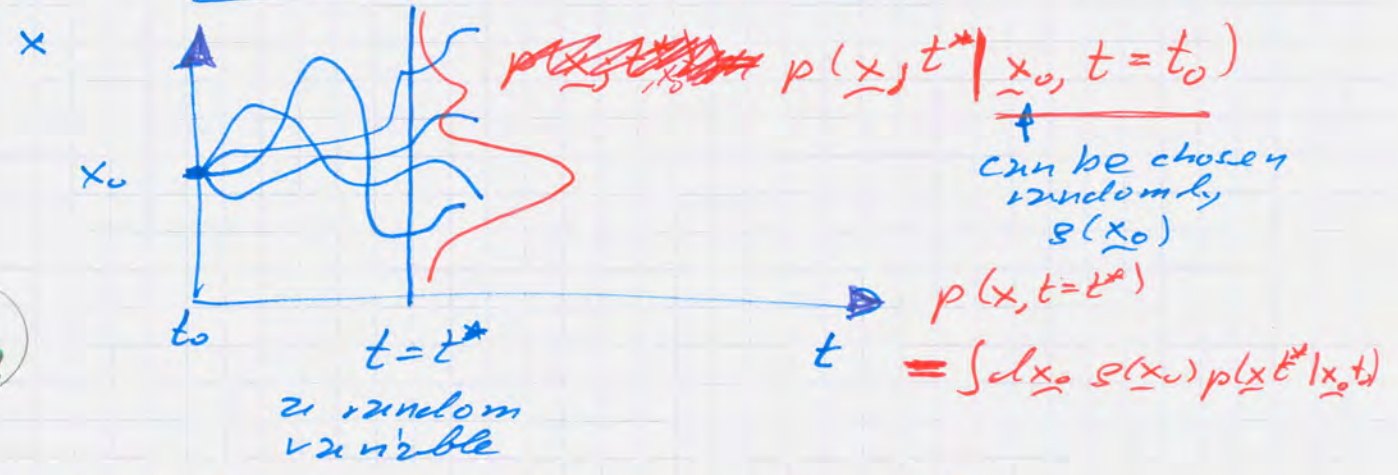
~~$p(t)$~~ $p(t+dt) = \underline{R(t+dt|t)} p(t)$
function of p_0



\underline{x} : state variables
 those are subject to

- (1) Fluctuations from baths
- (2) external forces acting on the system.

$\underline{x}(t)$: a stochastic process



include Detour!

$p(\underline{x}, t_0) \rightarrow p(\underline{x}, t^*) \rightarrow p(\underline{x}; t)$
 Undergoes a time evolution!

$\dot{p}(\underline{x}, t) = \mathbb{M} p(\underline{x}, t)$: master operator
 (Markov-processes!)

Markov:

Propagator

$$p^{(n)}(\underline{x}_n t_n, \dots, \underline{x}_0 t_0) = R(\underline{x}_n t_n | \underline{x}_{n-1} t_{n-1}) R(\underline{x}_{n-1} t_{n-1} | \underline{x}_{n-2} t_{n-2}) \dots R(\underline{x}_1 t_1 | \underline{x}_0 t_0) p(\underline{x}_0, t_0)$$

non-Markov:

$$p(\underline{x}, t) = R(t | t_0) p(t_0)$$

$$\dot{p}(t) = \underbrace{\dot{R}(t | t_0) R^{-1}(t | t_0)}_{= \mathbb{M}_t(t)} p(t)$$

Detour

normal vs. anomalous diffusion

normal:

$$\dot{p}(x,t) = D \frac{\partial^2}{\partial x^2} p(x,t)$$

more general $\dot{p}(x,t) = \frac{\partial}{\partial x} D(x) \frac{\partial}{\partial x} p(x,t)$

($\dot{p}(x,t) = -D(x) \frac{\partial p}{\partial x} \Rightarrow \dot{p} + \text{div}(j) = 0 \Rightarrow \dot{p} = \frac{\partial}{\partial x} D(x) \frac{\partial}{\partial x} p$)

position-position-correlation

$$\langle x(t)x(s) \rangle = \phi(t,s)$$

$$\langle [x(t) - x(s)]^2 \rangle = \langle x^2(t) \rangle + \langle x^2(s) \rangle - 2\phi(t,s)$$

stationary increments

$$\langle [x(t) - x(s)]^2 \rangle = \langle x^2(t-s) \rangle$$

Thus: $\phi(t,s) = \frac{1}{2} [\langle x^2(t) \rangle + \langle x^2(s) \rangle - \langle x^2(t-s) \rangle]$

anomalous diffusion

$$\langle [x(t) - x(s)]^2 \rangle = \langle x^2(t-s) \rangle = \underline{\underline{K(t-s)^\alpha}}, \quad t > s$$

example fract. Brownian motion

with $\langle x^2(t) \rangle = Kt^\alpha \Rightarrow \phi(t,s) = \frac{K}{2} (t^\alpha + s^\alpha - |t-s|^\alpha)$

independent increments

$t > s$; $\phi(t,s) = \langle x(t)x(s) \rangle = \langle [x(s) + \underbrace{\{x(t) - x(s)\}}_{=0}] x(s) \rangle$

$\Rightarrow \phi(t,s) = \langle x(t)x(s) \rangle = \langle x^2(s) \rangle$

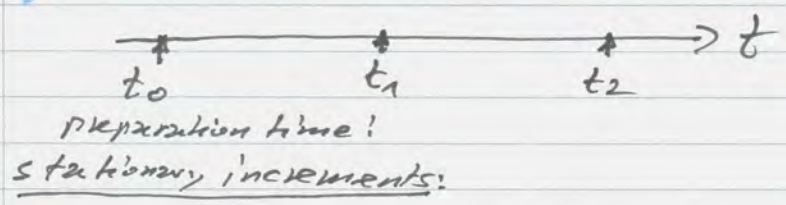
$$\Rightarrow \langle [x(t) - x(s)]^2 \rangle = \langle x^2(t) \rangle + \langle x^2(s) \rangle - 2\langle x^2(s) \rangle$$

$$= \langle x^2(t) \rangle - \langle x^2(s) \rangle$$

with $\langle x^2(t) \rangle = Kt^\alpha$

$$\Rightarrow \langle [x(t) - x(s)]^2 \rangle = K(t^\alpha - s^\alpha)$$

same only for $\alpha = 1$ (normal diffusion)



$$\langle [x(t_2 - t_0) - x(t_1 - t_0)]^2 \rangle = \langle x^2(t_2 - t_0 - \{t_1 - t_0\}) \rangle = K(t_2 - t_1)^\alpha$$

NO AGE

uncorrelated increments
(independent)

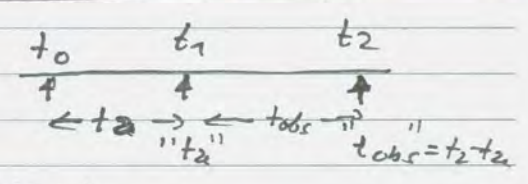
$$\langle [x(t_2 - t_0) - x(t_1 - t_0)]^2 \rangle = K[(t_2 - t_0)^\alpha - (t_1 - t_0)^\alpha]$$

→ can determine AGE of system dynamics
(CTRW, ..., Fractional F-1) - e.g.s.)

age of the system at the beginning of observation

$$t_{\text{age}} = t_1 - t_0$$

$$t_{\text{observation}} = t_2 - t_{\text{age}}$$



~~$$t_{\text{age}} = t_2 - t_0; t_{\text{obs}} + t_{\text{age}} = t_2 - t_{\text{age}} + t_{\text{age}}$$~~

$$\langle x^2(t_{\text{obs}}, t_2) \rangle = K[(t_{\text{obs}} + t_2)^\alpha - t_{\text{age}}^\alpha] = K t_2^\alpha \left[\left(\frac{t_{\text{obs}}}{t_2} + 1 \right)^\alpha - 1 \right]$$

$t_{\text{obs}} \ll t_2$

full aging

$$\langle x^2(t_{\text{obs}}, t_2) \rangle \approx K \alpha t_2^{\alpha-1} t_{\text{obs}}$$

$$\sim \left(1 + \frac{t_{\text{obs}}}{t_2} \right)^\alpha$$

age-dependent diffusion

examples

I. Fokker-Planck-eg.:

$$\dot{p}(\underline{x}, t) = - \frac{\partial}{\partial \underline{x}} \underline{j}(\underline{x}, t) \Leftrightarrow \dot{p} + \text{div} \underline{j} = 0$$

conservation of probability,

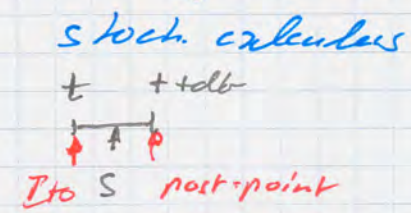
$$= - \frac{\partial}{\partial \underline{x}} \left\{ \underline{f}(\underline{x}) p(\underline{x}, t) - \underline{D}(\underline{x}) \frac{\partial}{\partial \underline{x}} p(\underline{x}, t) \right\}$$

⇕ relation to a stochastic diff. eq.

$$\underline{D}(\dots) = \underline{g}(\dots) \underline{g}^T(\dots) \quad \dot{\underline{x}} = \underline{f}(\underline{x}) + \underline{g}(\underline{x}) \frac{d\underline{w}(t)}{dt}$$

Ito $\rightarrow \underline{D}(\underline{x}) \frac{\partial^2}{\partial \underline{x}^2} p(\underline{x}, t)$

Stratonovich $\rightarrow \frac{\partial}{\partial \underline{x}} \underline{g}(\underline{x}) \frac{\partial}{\partial \underline{x}} \underline{g}(\underline{x}) p(\underline{x}, t)$



Hänggi (postpoint) $\frac{\partial}{\partial \underline{x}} \underline{D}(\underline{x}) \frac{\partial}{\partial \underline{x}} p(\underline{x}, t)$ (transport form)

II. Liouville eg. $\underline{x} \rightarrow$ phase space $(q_1, p_1, q_2, p_2, \dots, q_n, p_n)$

Poisson bracket: $\{f, g\} = \sum_i \left\{ \frac{\partial f}{\partial p_i} \frac{\partial g}{\partial q_i} - \frac{\partial f}{\partial q_i} \frac{\partial g}{\partial p_i} \right\}$

$$\dot{p}(\underline{x}, t) = \{ \mathcal{H}(\underline{x}), p(\underline{x}, t) \}$$

Now: perturbation acting on System only

$$\mathcal{H}_0 \rightarrow \mathcal{H}_0 = \lambda(t) Q(\underline{x}) ; \quad H_0 = \frac{p^2}{2m} + U(x)$$

$$m \ddot{x} = - \frac{\partial U}{\partial x} + \lambda(t) + \sqrt{2\lambda(t)} \frac{dw}{dt}$$

$$\Leftrightarrow \mathcal{T}(t) = \mathcal{T}_0 \bullet \lambda(t) \frac{\partial}{\partial \underline{x}} ; \quad \dot{p}(\underline{x}, t) = \mathcal{T}_0 p(\underline{x}, t) - \lambda(t) \frac{\partial}{\partial \underline{x}} p(\underline{x}, t)$$

Linear Response Theory

$$\Pi_{total} = \underbrace{\Pi_0}_{\text{no perturbation}} + \underbrace{\Pi_{ext}(t)}_{\text{imposed perturbation}}$$

we set: $\Pi_{ext}(t) \equiv \lambda(t) \Omega$

$$\begin{aligned} \dot{\rho}(x,t) &= \int \Pi_{total}(x,y;t) \rho(y,t) dy \\ &= \int \{ \Pi_0(x,y) + \lambda(t) \Omega(x,y) \} \rho(y,t) dy \end{aligned}$$

conservation of probability

$$\Rightarrow \int \dot{\rho}(x,y;t) dx = 0 \Leftrightarrow \int \dot{\Pi}_0(x,y) dx = 0$$

~~$\int \dot{\Pi}_0(x,y) dx = 0$~~
& ~~$\int \dot{\Omega}(x,y) dx = 0$~~
 $\int \dot{\Omega}(x,y) dx = 0$

Dyson-Eq.

$$\dot{\rho} = (\Pi + \Pi_{ext}) \rho$$

$$\rho(t) = R(t|s) \rho(s) ; R(t|s): \text{Propagator}$$

$$\begin{aligned} \Rightarrow \dot{\rho}(t) &= \dot{R}(t|s) \rho(s) \\ &= \underbrace{\Pi(t) R(t|s)}_{\rho(t)} \rho(s) = \Pi(t) \rho(t) \end{aligned}$$

$$\boxed{\dot{R}(t|s) = (\Pi_0 + \Pi_{ext}(t)) R(t|s)} ; R(t+t) = R(t|t) = \mathbb{1}$$

$\langle x | R(t_0|t_0) | y \rangle = \delta(x-y)$

solution: $t \geq t_0 ; s \geq t_0 ; t \geq s$

EXACT: $R(t|t_0) = R_0(t|t_0) + \int_{t_0}^t R_0(t|s) \Pi_{ext}(s) R(s|t_0) ds$

$$\dot{R}(t|t_0) = \Pi_0 R_0(t|t_0) + \Pi_0 \int_{t_0}^t R_0(t|s) \Pi_{ext}(s) R(s|t_0) ds$$

$$\Pi_0 R(t|t_0)$$

$$+ \underbrace{R_0(t|t) \Pi_{ext}(t)}_{\mathbb{1}} R(t|t_0)$$

$$= (\Pi_0 + \Pi_{ext}(t)) R(t|t_0) \quad \text{q.e.d.}$$

Linear Response

15

replace $R(t|s)$ with unperturbed solution

$$R(t|s) \Rightarrow R_0(t|s) = \exp T_0^{\dagger} (t-s)$$

$$\rho(t) = \rho_0(t) + \int_{t_0}^t R_0(t|s) \lambda(s) \rho_0(s)$$

from now on $\rho_0 = \bar{\rho}$: stationary solution $T_0^{\dagger} \bar{\rho} = 0$

consider an observable $x(t)$

Linear response $\langle \delta x(t) \rangle = \langle x(t) \rangle_{\rho(t)} - \langle x(t) \rangle_{\bar{\rho}}$

$$:= \int_{t_0}^t \chi(t-s) \lambda(s) ds$$

W. Leve

$$\chi(t-s) = \Theta(t-s) \int \int dx dy x \{ \Omega \bar{\rho} \}(y) R_0(x; t-s|y)$$

↑
causality

Fluctuation - Theorem (Linear Response)

P. H.; Helv. Phys. Acta 51, 202 (1978); Phys. Rep. 88: 207 (1982)

Define: $\varphi(x) \bar{\rho}(x) = (\Omega \bar{\rho})(x)$; $\int \varphi(x) \bar{\rho}(x) = \int (\Omega \bar{\rho})(x) dx$

$$\Rightarrow \langle \varphi(x) \rangle_{\bar{\rho}} = \int \underbrace{(\Omega \bar{\rho})(x)}_{[\Omega \bar{\rho}](x)} dx = 0$$

is stationary correlation!

$$\Rightarrow \chi(t-s) = \chi(t) = \Theta(t-s) \langle x(t) \delta \varphi(0) \rangle_{\bar{\rho}}$$

$$= \Theta(t-s) \langle \delta x(t) \delta \varphi(0) \rangle_{\bar{\rho}}$$

Linear $:= \Theta(t-s) \langle \delta x_t \delta \varphi(x(0)) \rangle_{\bar{\rho}}$

"Response measures the stationary correlation between $\delta x = x(t) - \langle x \rangle_{\bar{\rho}}$ & $\varphi(x(0))$

alternative result for $\chi(\tau)$

$$\vec{\pi}(\tau) = \left[\vec{\pi}_0 + \lambda(\tau) \mathcal{R} \right]_{\text{prescribing frozen}} = 0$$

linear response δp_2 :

$$\vec{\pi}_0 \delta p_2 + (\mathcal{R} \bar{p}) \lambda(\tau) = 0$$

define: $\delta p_2(x; \lambda(\tau)) := \psi(x) \bar{p}(x) \lambda(\tau)$

$$\Rightarrow [\mathcal{R} \bar{p}](x) = - \int \vec{\pi}_0(x, z) \psi(z) \bar{p}(z) dz$$

again one can show $\langle \psi(x) \rangle_{\bar{p}} = 0$

$$\Rightarrow \chi(\tau) = - \theta(\tau) \int \int \int dx dy dz \underbrace{R_0(x; \tau | y)} \vec{\pi}_0(y, z) \psi(z) \bar{p}(z)$$

$$R_0 = \exp(\vec{\pi}_0 \tau) \text{ with } \frac{dR_0}{d\tau} = \vec{\pi}_0 R_0(\tau) = \underline{R_0(\tau) \vec{\pi}_0}$$

$$= - \theta(\tau) \frac{d}{d\tau} \int \int dx dz \delta x R_0(x; \tau | z) \psi(z) \bar{p}(z)$$

$$\boxed{\chi(\tau) \stackrel{!}{=} - \theta(\tau) \frac{d}{d\tau} \langle \delta x(\tau) \psi(x(\tau)) \rangle_{\bar{p}}}$$

2nd Fluctuation-~~Theorem~~

Examples

isolated system $\rho(X, t) = \{ (H_0 + H_{ext}), \rho \}$
 Liouville eq.

$$H_{ext}(t) = -\lambda(t)x$$

$$\Rightarrow \Omega = -\{x, -\} \quad \& \quad \bar{\rho}(x) = Z^{-1} \exp(-\beta H_0(x))$$

canonical Gibbs!

$$\chi(x, \bar{\rho}) \equiv \int \Omega \bar{\rho} \delta x \Rightarrow \chi(x) = \{x, H_0(x)\} \beta = \beta \dot{x}$$

likewise: $\psi(x) = \beta x$

Therefore: $\chi(t) = \Theta(t) \beta \langle \delta x(t) \dot{x}(0) \rangle_{\bar{\rho}=reg.}$

$$= -\Theta(t) \beta \cdot \frac{d}{dt} \langle \delta x(t) \delta x(0) \rangle_{\bar{\rho}=reg.}$$

$$= -\Theta(t) \frac{1}{k_B T} \frac{d}{dt} \langle \delta x(t) \delta x(0) \rangle$$

Kubo - classical Fluctuation-Dissipation
 (1964) Theorem

Quantum Generalization Callen-Welton (1951)

$$\chi_{xx}(\tau) = \frac{i\theta(\tau)}{\hbar} \langle [x(\tau), x(0)] \rangle_{\beta}$$

$$= -\theta(\tau) \int_{\beta}^{\beta+\hbar} \langle x(-i\hbar\lambda) \dot{x}(\tau) \rangle_{\beta} d\lambda$$

$$(-\theta(\tau) \beta \langle \dot{x}(\tau) \dot{x}(0) \rangle)$$

$$\chi''(\omega) = \frac{1}{\hbar} \tanh(\hbar\omega\beta/2) S_{xx}(\omega)$$

$\uparrow \frac{1}{2} \langle (\delta x(\tau)\delta x(\omega) + \delta x(\omega)\delta x(\tau)) \rangle_{\beta}$
Symmetrized

Therefore: ~~$S_{xx}(\omega) = \hbar \coth(\hbar\omega\beta/2)$~~

$$S_{xx}(\omega) = \hbar \coth(\hbar\omega\beta/2) \chi''(\omega)$$

one measures the response to the single-time observable:

$$\dot{x}(t) = \langle \dot{x}(t) \rangle - \langle \dot{x}(t) \rangle_{\text{eq}}$$

One does not do a two-time measurement of a quantum correlation!